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Collaborative Signal Processing for Sensor Networks

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BAE SYSTEMS/MIT Collaborative Signal Processing Tasks

- **Networked Tracking - BAE SYSTEMS**
  - **improve data association between nodes**
- **Distributed Network Processing - MIT**
  - **lower field power requirements**

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Agenda

- Algorithm
- SITEX 02 Data Collection
- Results of data analysis to date
  - Tripwire algorithm
  - Personnel detection
- Future plans

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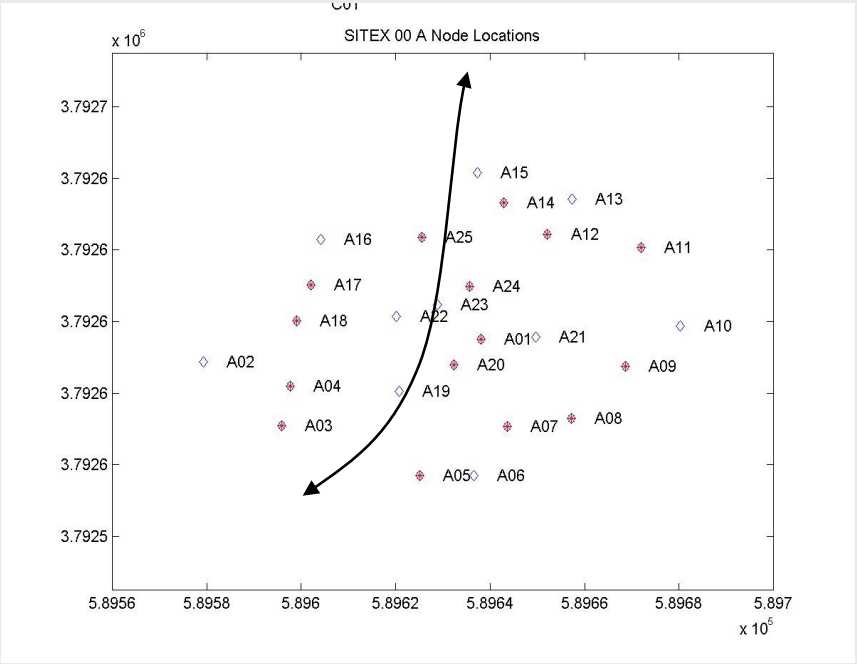
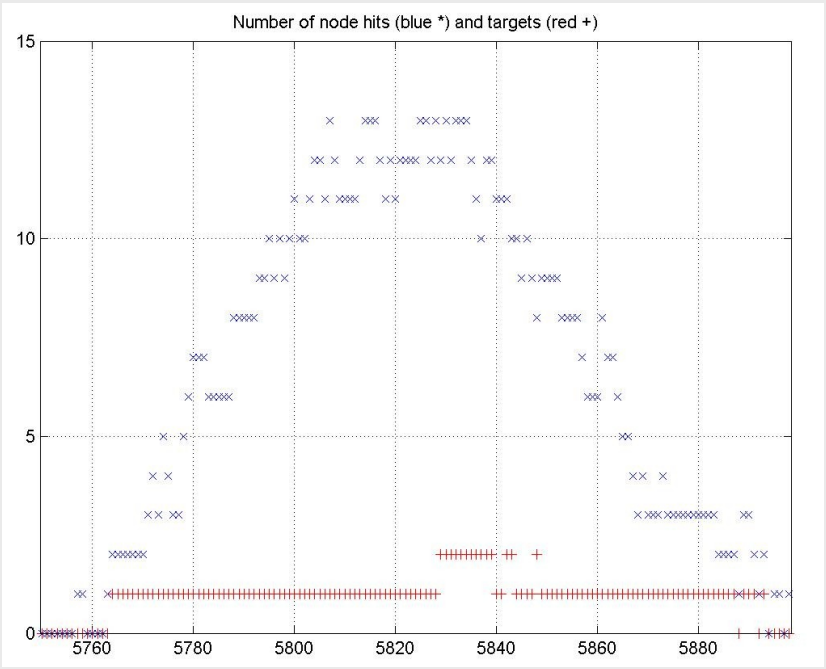
Sensor system must reduce multiple node data to single output





- **Two vehicles passing through 13 node cluster**

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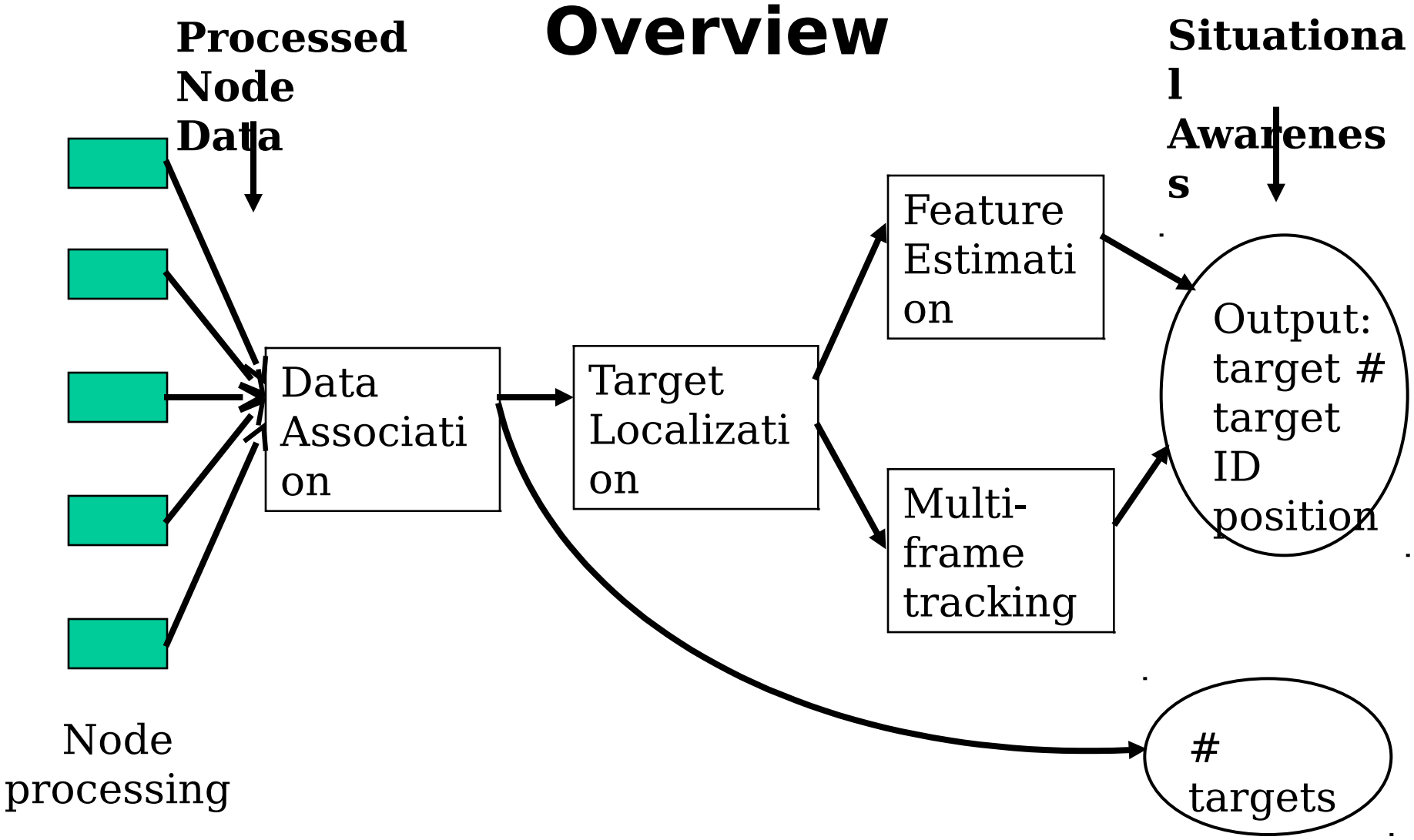
Situational Awareness Processing Overview



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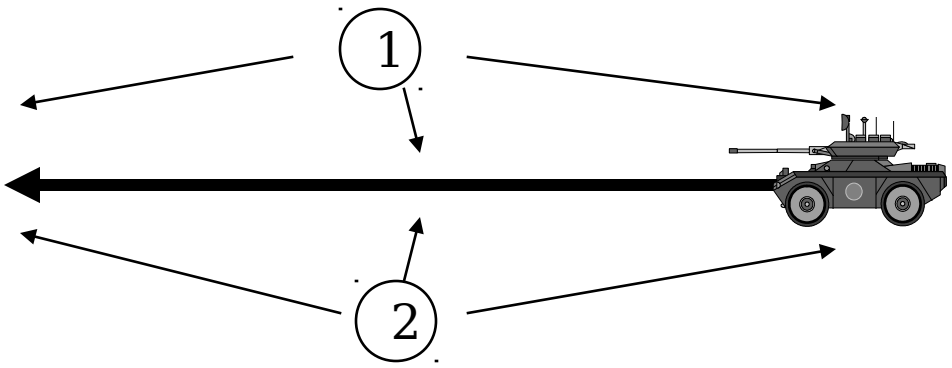
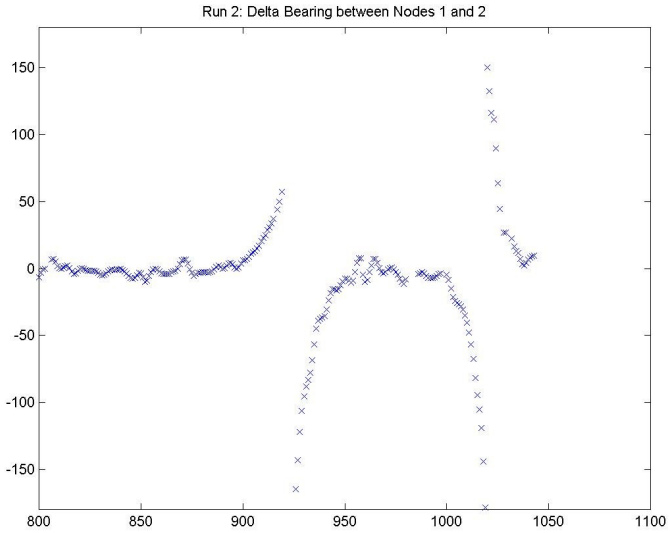
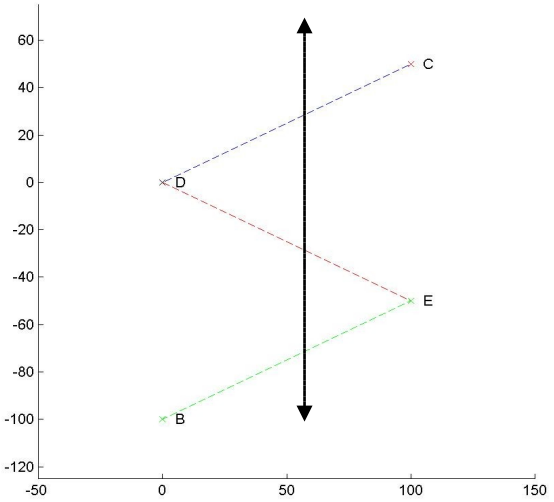
Data Association Using Tripwire



- From tripwire nodes, bearing to target is same at infinity, and opposite at crossing
- Can resolve multiple targets
- Estimate position between nodes based on size of bearing difference





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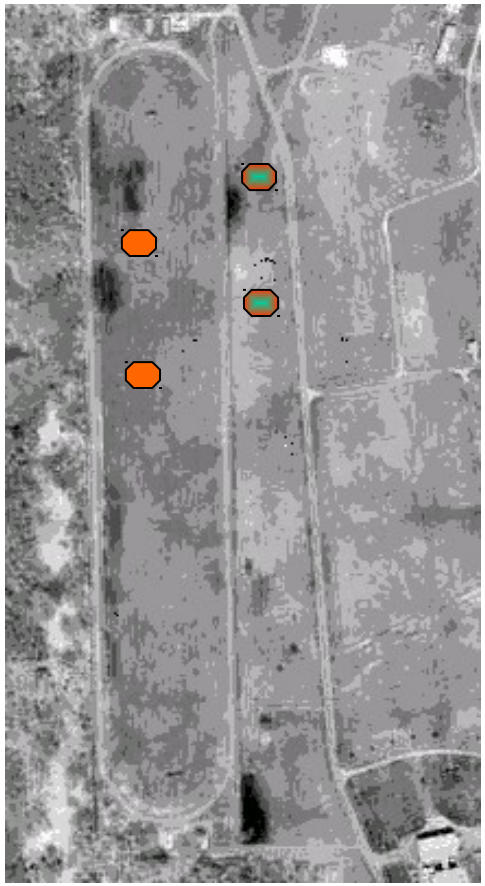
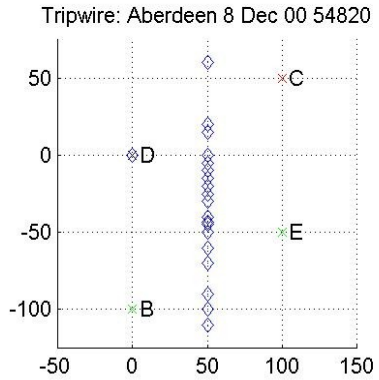
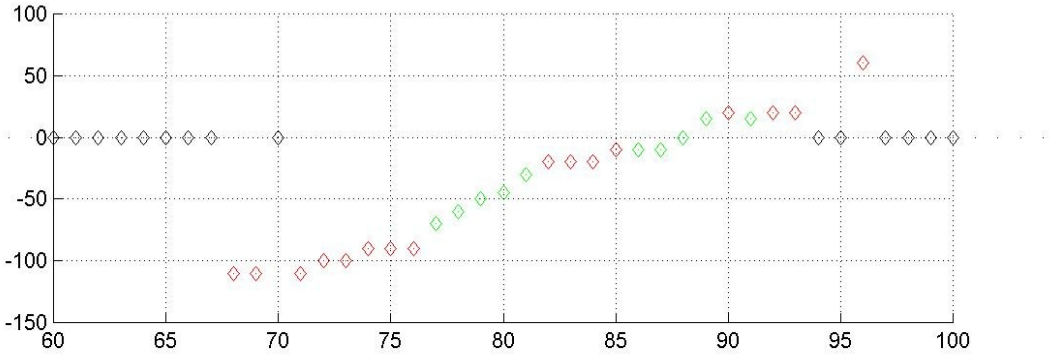
Aberdeen Dec 00 Tripwire







- **Diamond configuration**
  - **100m spacing each axis**

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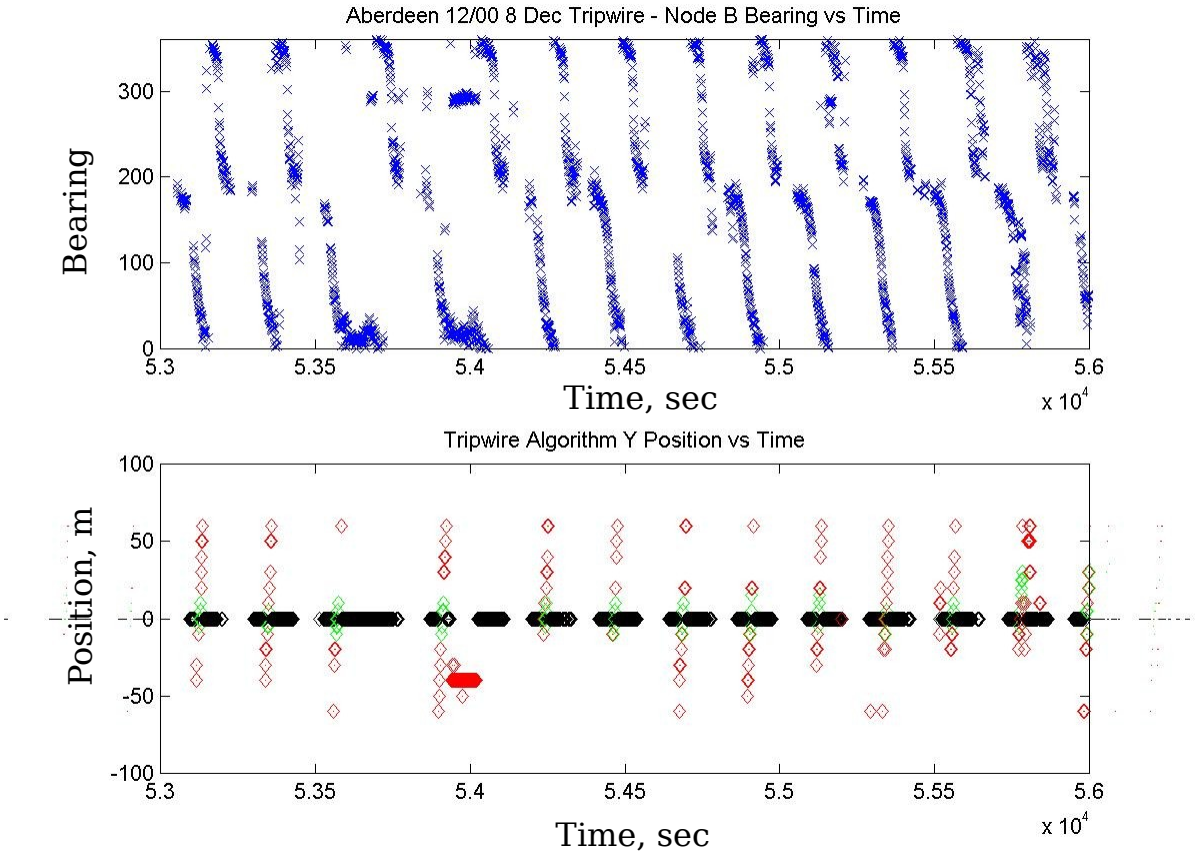
Example over 13 transits



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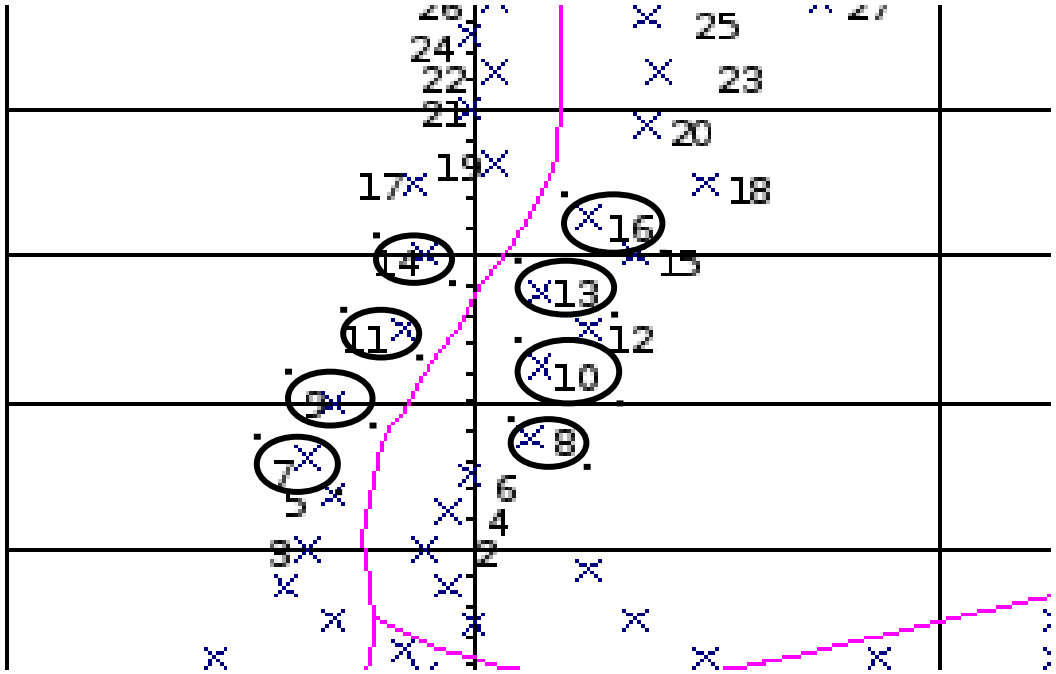
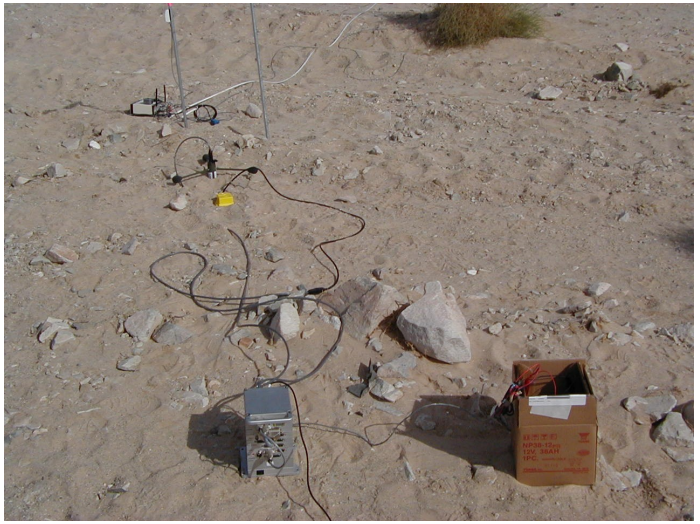
SITEX 02 Node Locations



- **12 thru 14 November**
- **Nodes 7, 8, 9, 10, 11, 13, 14, 16**
- **Average Node Separation = 41.6m**

BAE SYSTEMS Sensor System

- 3 microphone array
- 1-axis or 3-axis seismic array
- a/d, fs = 1024 Hz
- on-node processing & storage



- fusion on gateway node

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Software Configuration

MIUGS

Senserv

- calculate bearing
- sends bearing via serial link
- log to file

RS-232

WINS 2.0

BearingServer

- puts data into twrec repository

BearingClient

- get twrec data, publishes via diffusion
- logs to local file

Tripwire

- subscribes to all nodes
- logs all bearings to file
- run tripwire
- logs positions to file
- outputs data

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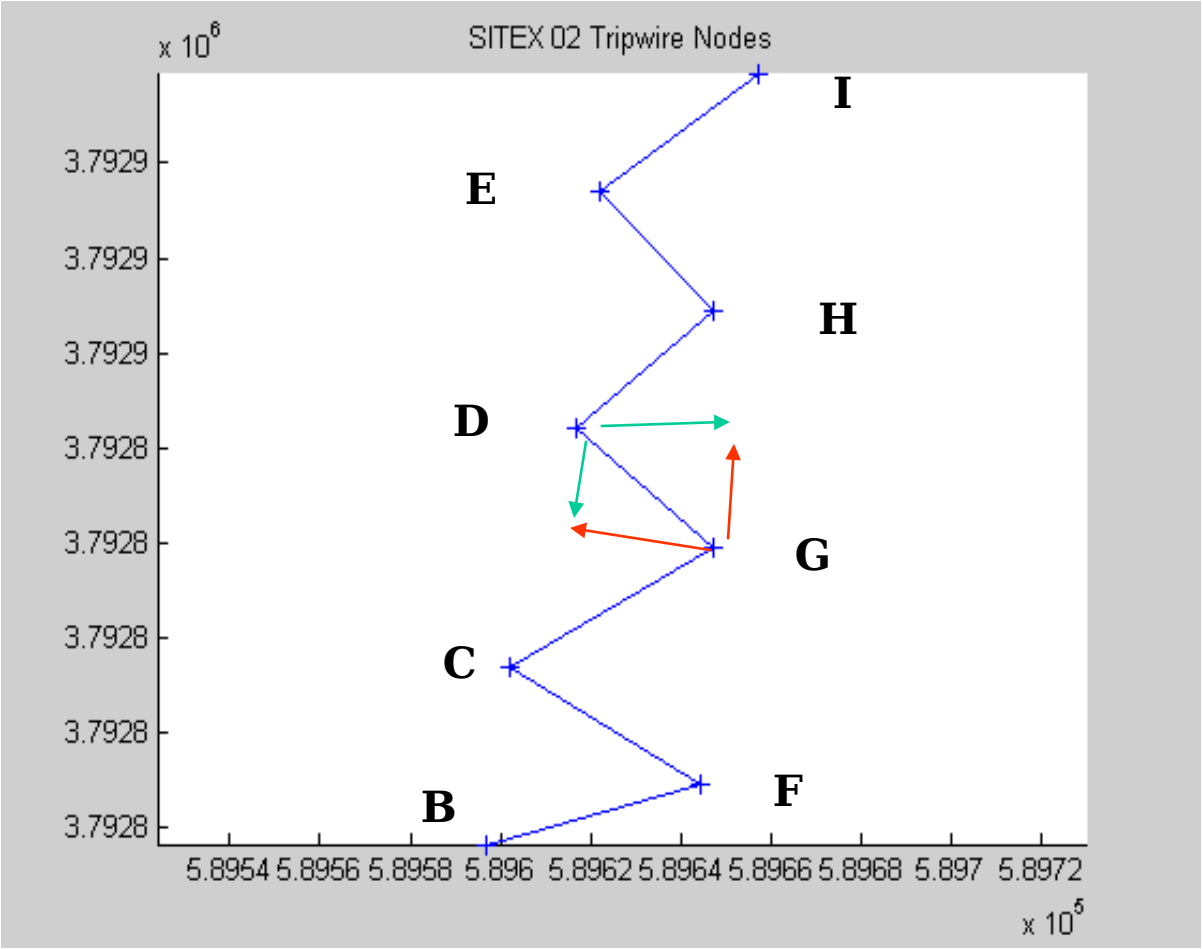
Node Pairs and Gates



Tracking results: baseline system

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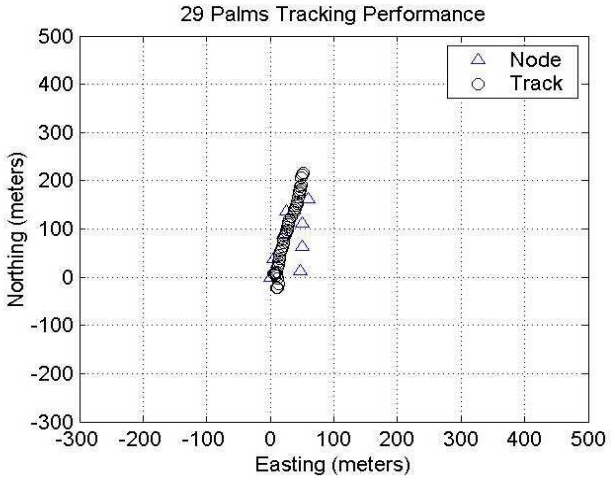

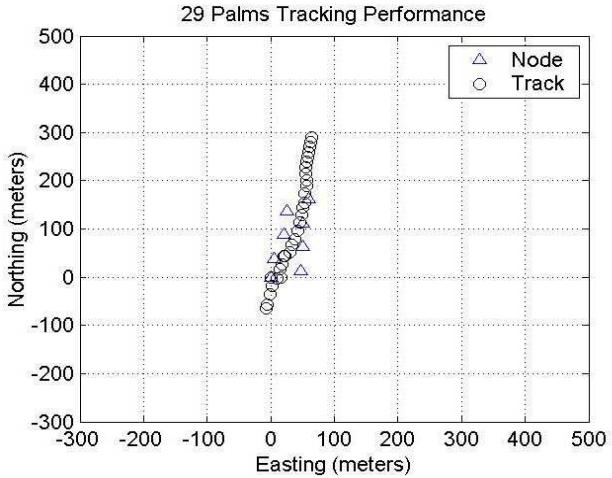

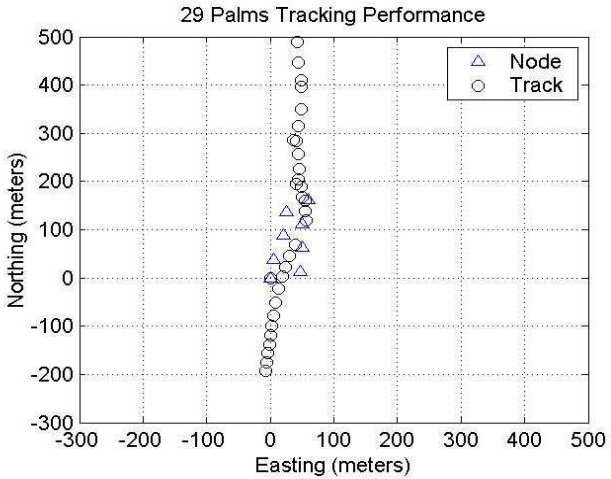

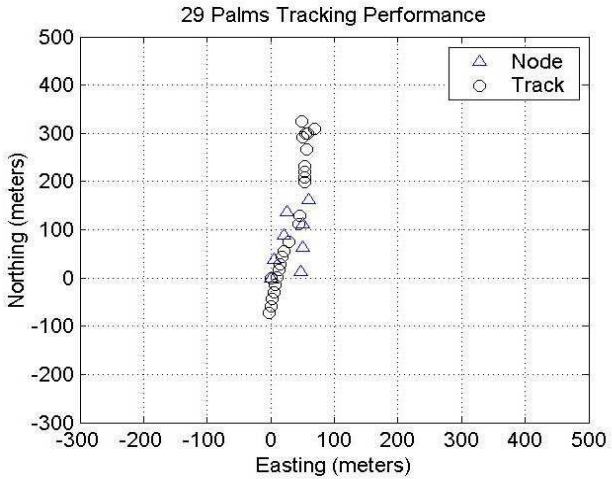

14 Nov, > 2300 GMT

Tracking results - baseline system

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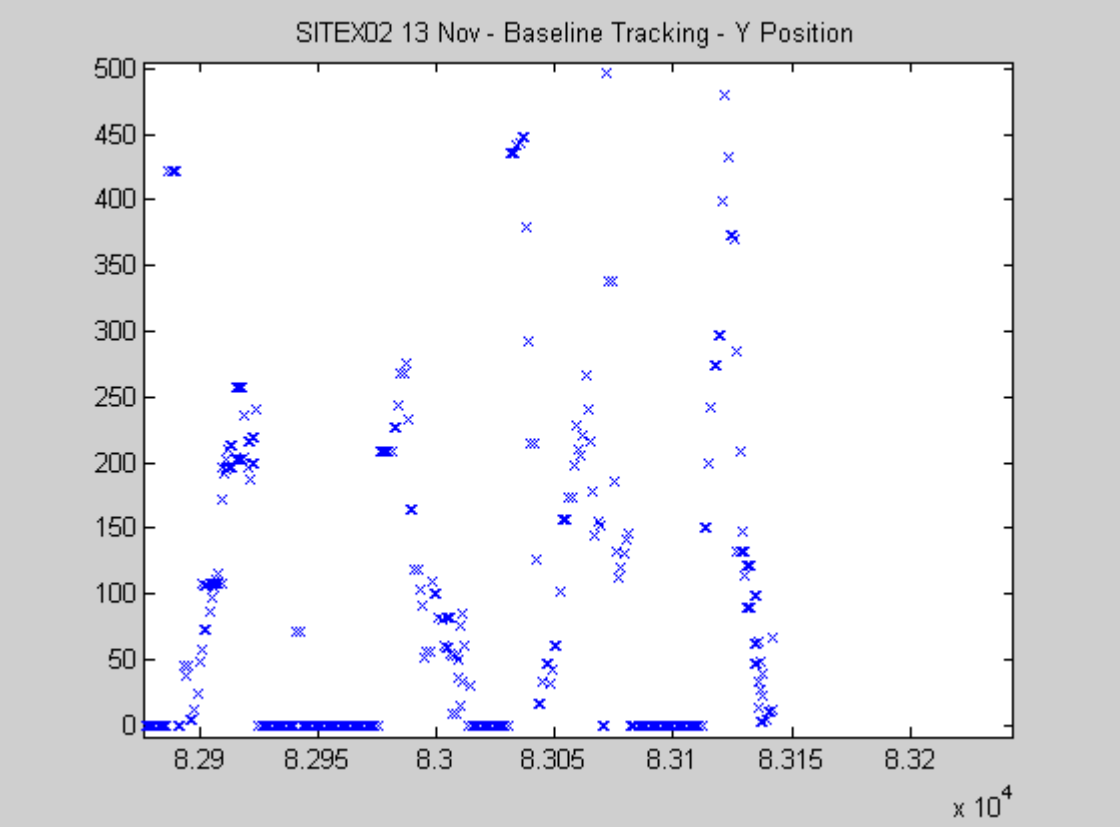
Y, m



Time, seconds

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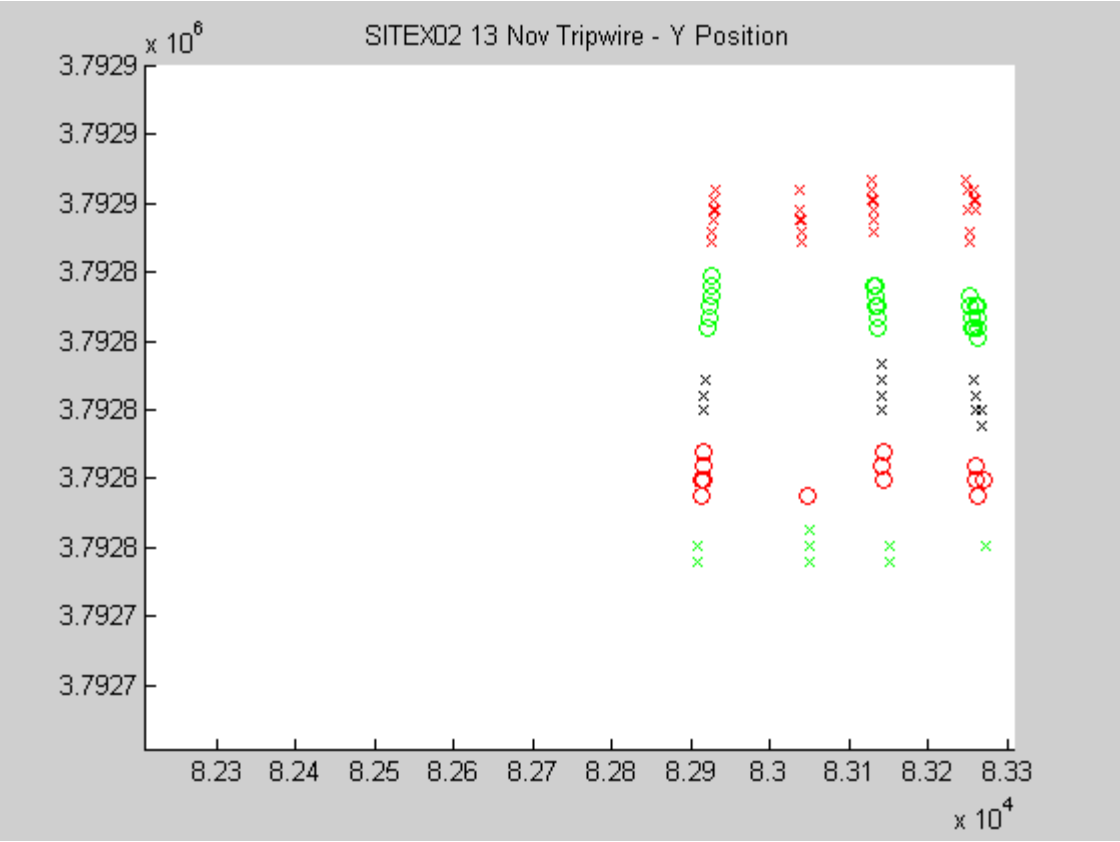
Tracking results - Tripwire



Y, m

Time, seconds

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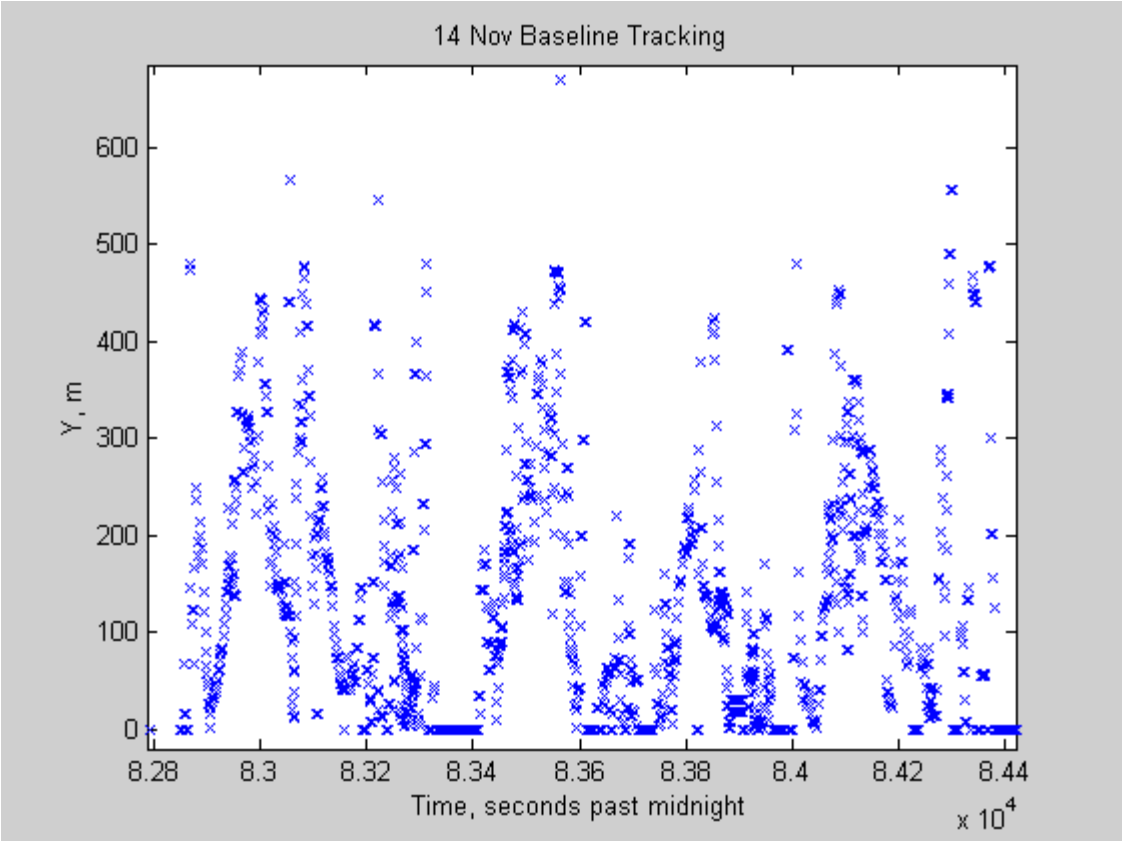
Multiple Single Vehicle Passes - Baseline Tracking

Y position, meters



Time, seconds past midnight

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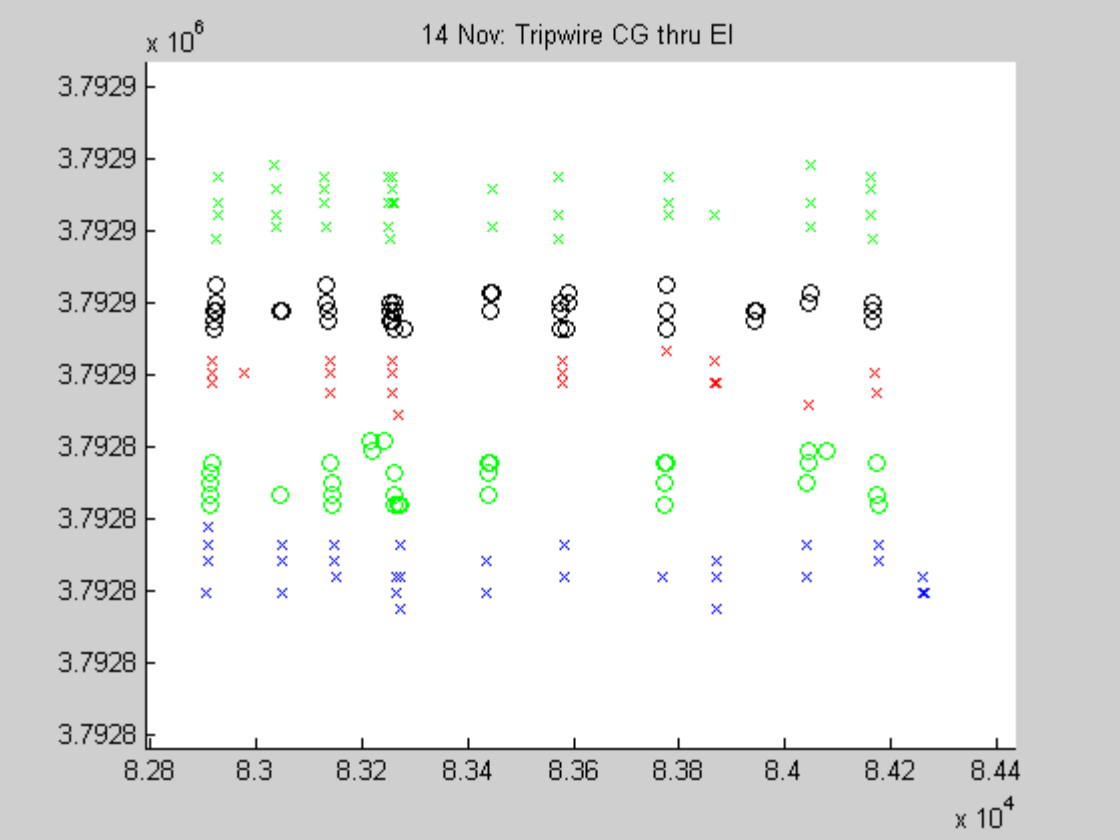
Multiple Single Vehicle Passes - Tripwire

Y position, meters, 200m span



Time, seconds past midnight

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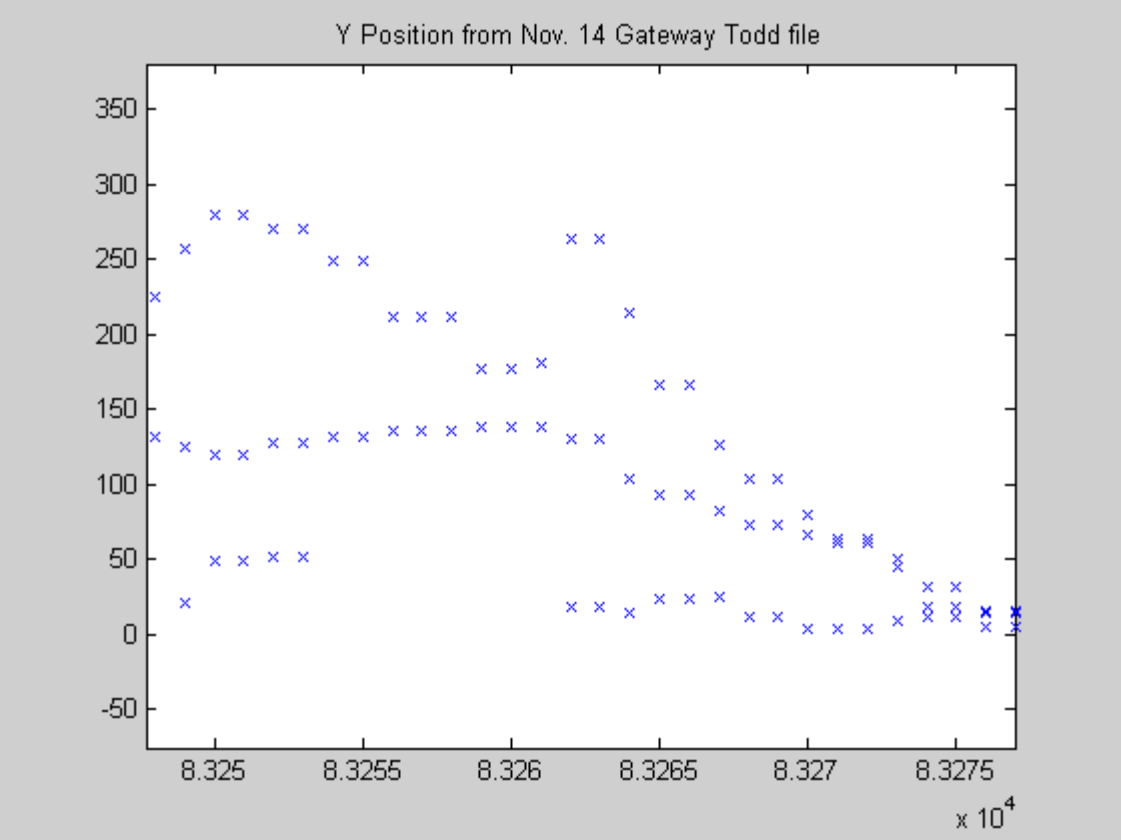
SITEX 02 Results - Two Targets - Baseline Tracking

Y position, meters (50m per box)



Time, seconds past midnight (5s per box)

SITEX 02 Results - Two Targets Tripwire

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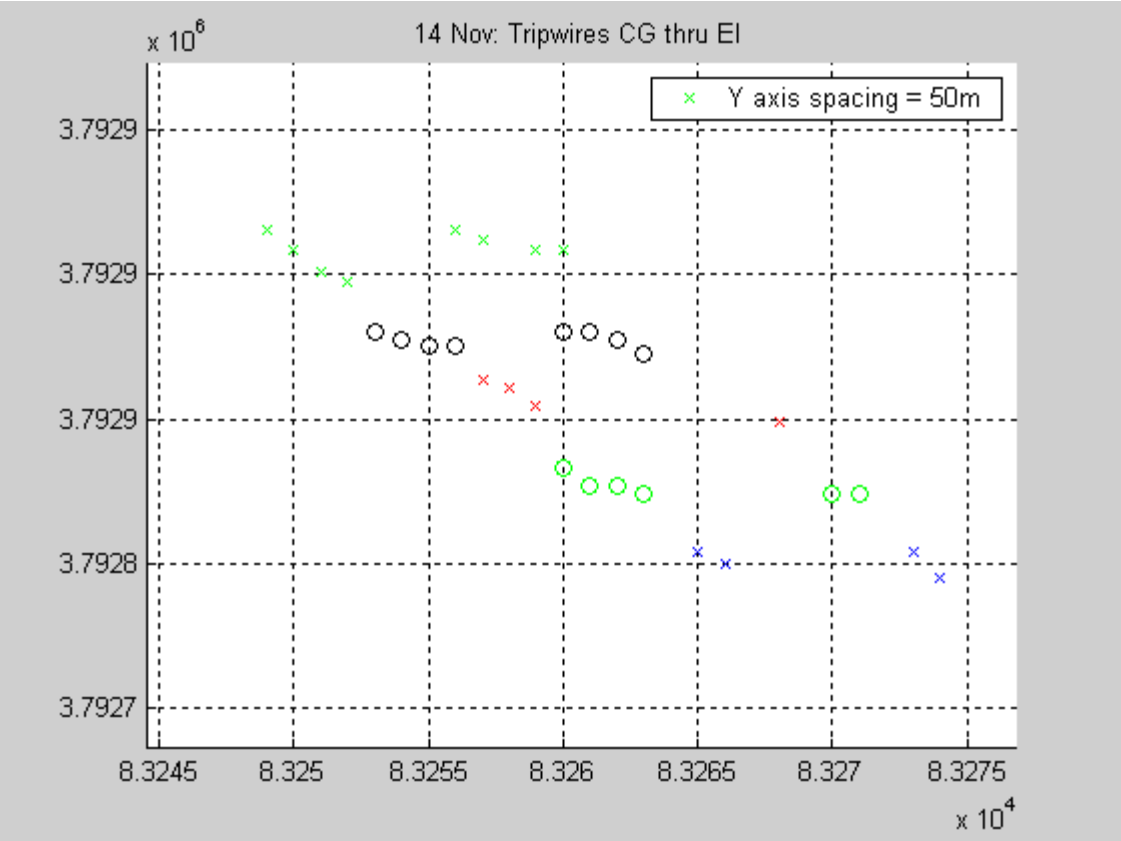
Y position, meters (50m per box)



Estimated target separation = 40m - 50m

Time, seconds past midnight (5s per box)

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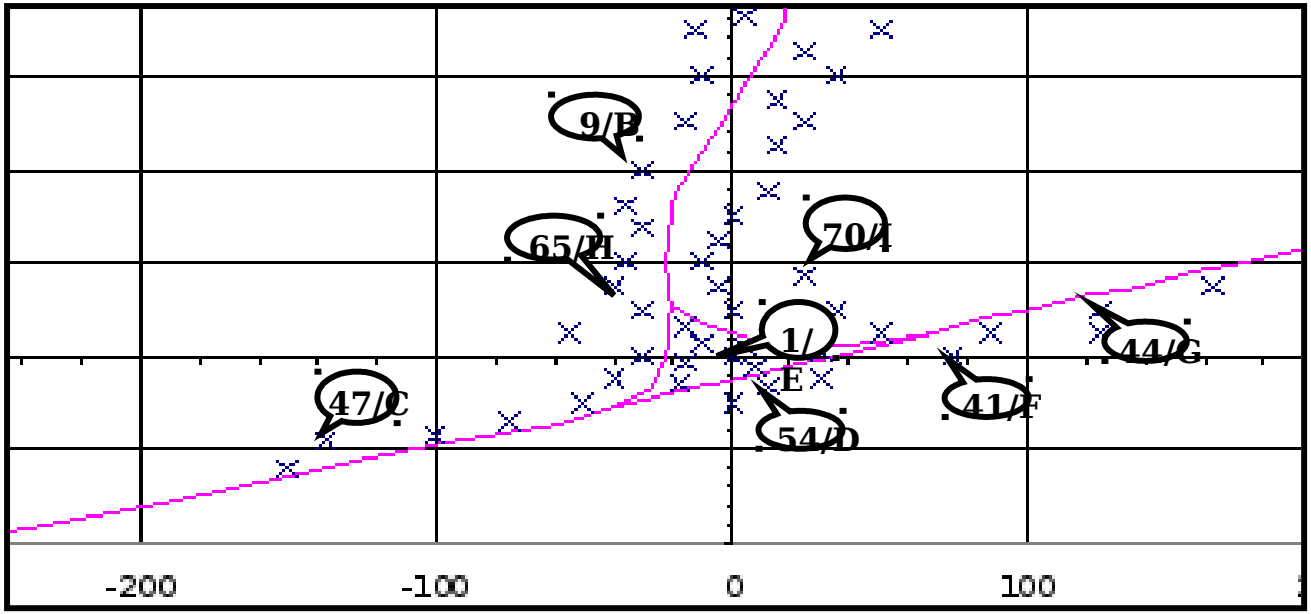
Tripwire Analysis Status

- Analyzing data for 12, 13, 14 Nov
- Awaiting log, video, ground truth information
- Second configuration for 15 Nov



Tripwire Algorithm Effectiveness

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- **Provides accurate position**
- **Provides accurate count for target spacing > node spacing**
- **Low processing requirements on node**
  - **avoids combinatorial explosion (e.g. LOB intersection) since small potential number of targets**
- **Scalable over number of nodes**
  - **one report per target**
- **But**
  - **Dependent on good data from nodes**
  - **Not helpful when target is outside node grid**

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SITEX 02 Personnel Analysis

- 12 Nov - column of 342 Marines
  - West to intersection, paused, then went North

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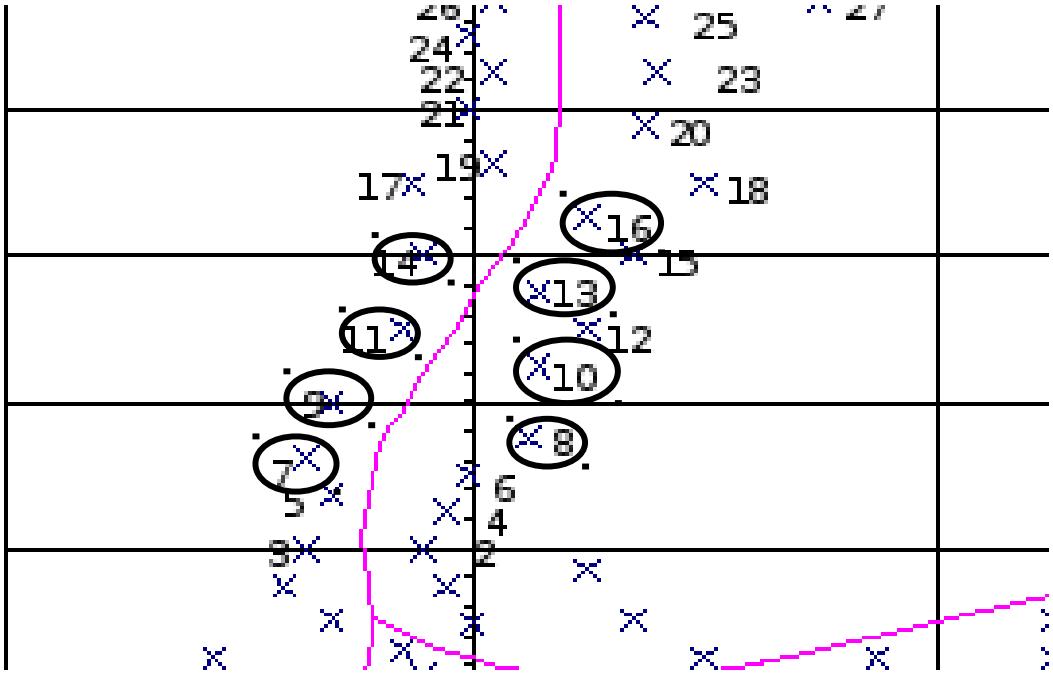
Personnel Tracking Set-up

- 3 axis geophones deployed to east of road



H - 13m

G - 12m

F - 23m

E - 30m

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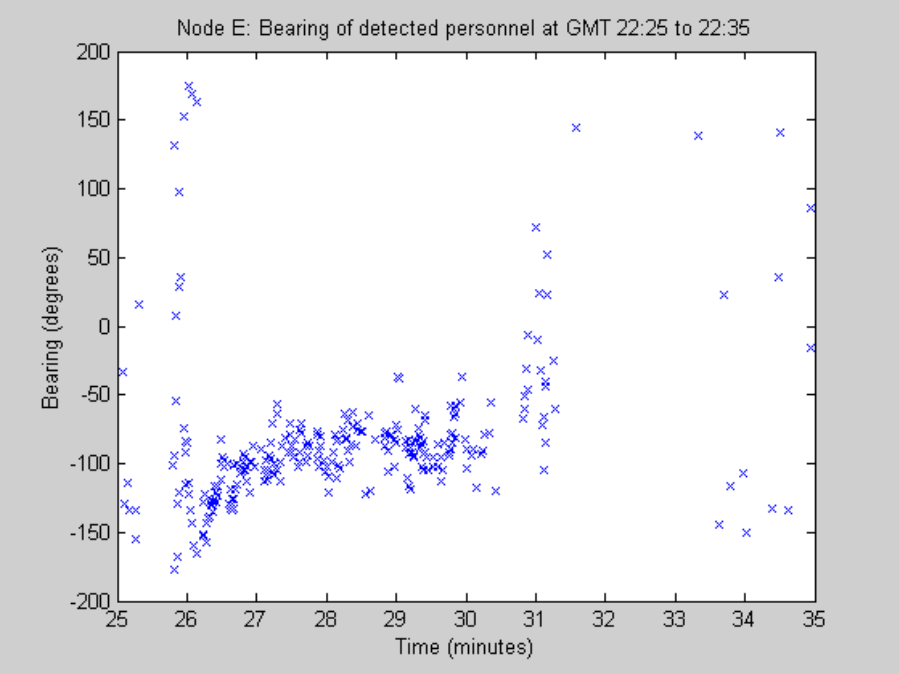
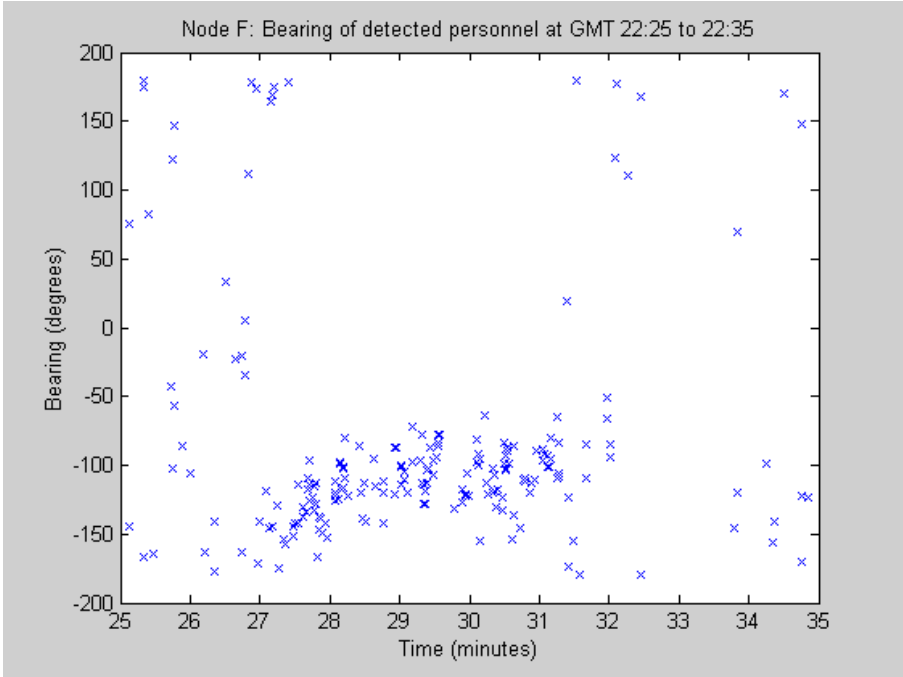
SITEX 02 Personnel Analysis





Troops moving SW to NE

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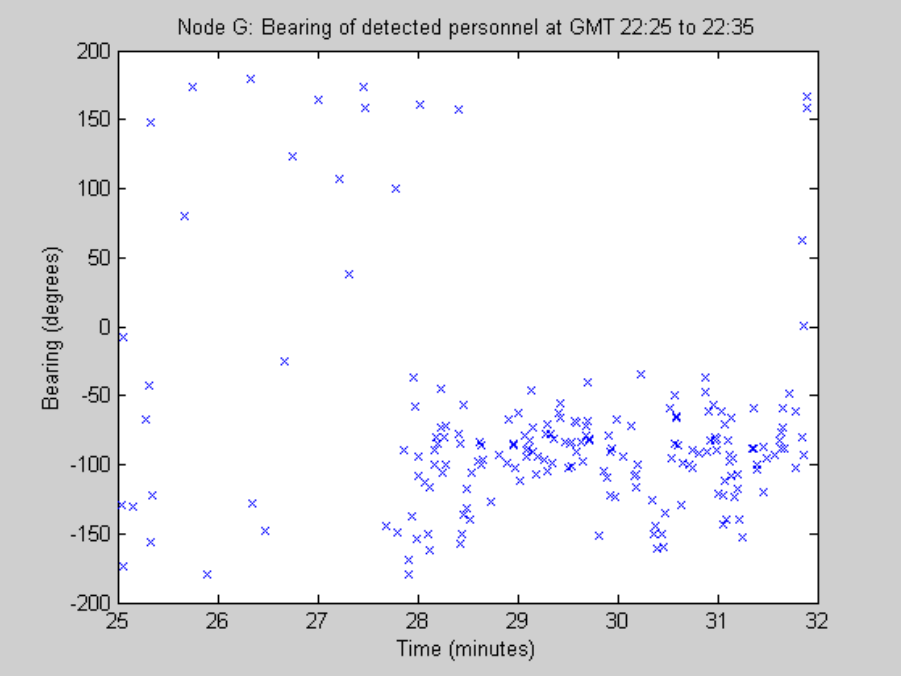
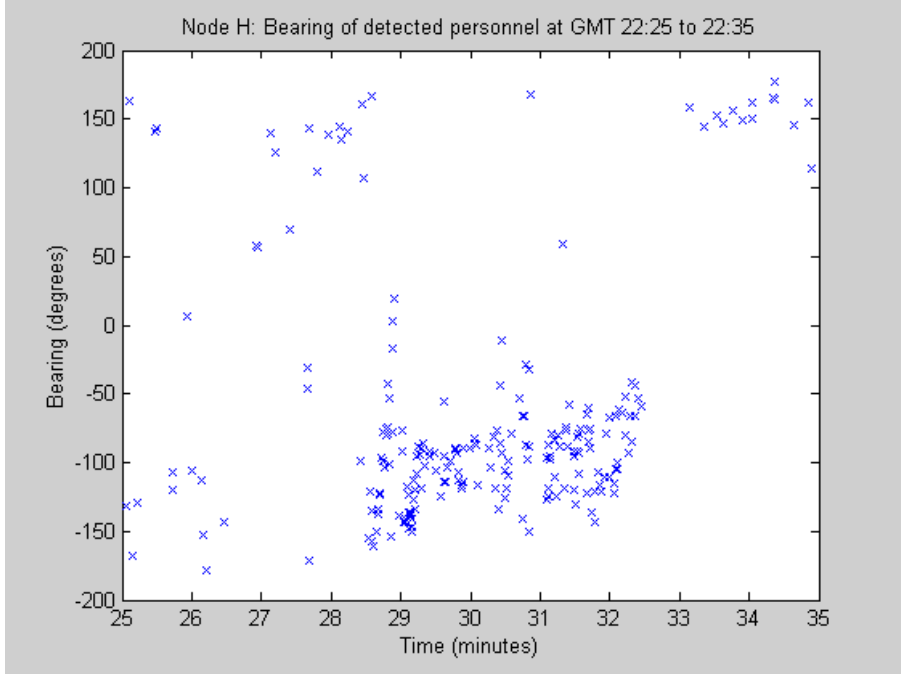
SITEX 02 Personnel Analysis





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Future Work

- **Analyze additional SITEX 02 data**
  - **bearing tripwire**
  - **doppler tripwire**
- **Data Quality Evaluation**
  - **comparing data from cooperating nodes to identify nodes with bad data**
- **Cued aerial observer**
  - **UAV or parachute viewer**
  - **photo, targeting**